

# SCADA

SYSTEMS & EQUIPMENT



**Keppel**

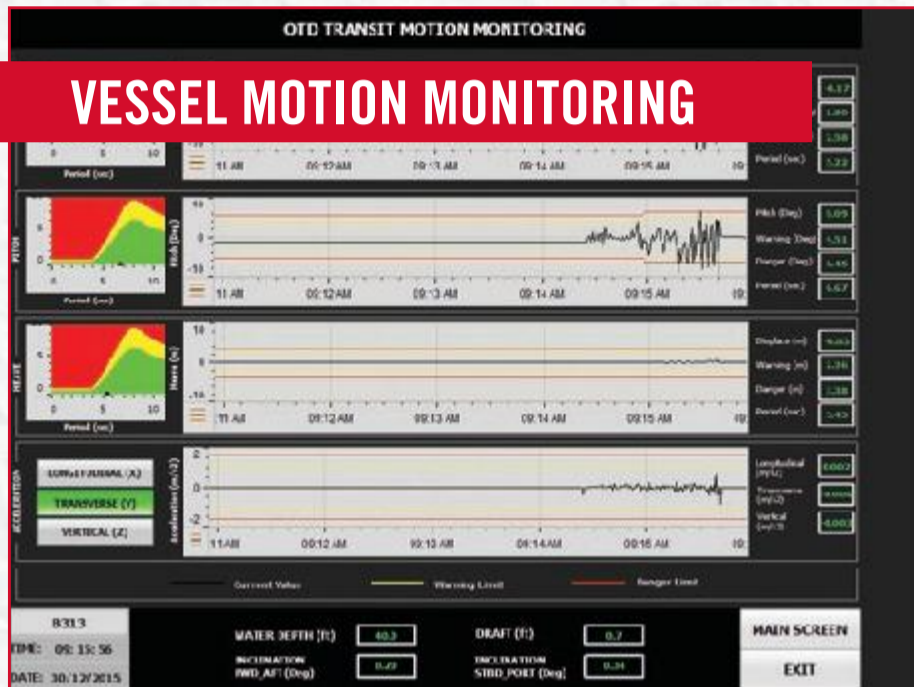
**Offshore Technology  
Development**

## SCADA SYSTEMS

With the increasing demand for energy around the world, petroleum, natural gas, facilities such as oil rigs, offshore platforms, and marine vessels have become important assets. Maintaining economic progress is strongly dependent on having reliable monitoring and control systems for expensive Offshore & Marine infrastructures that significantly help in inspecting and eradicating unforeseen circumstances or human errors.

At Offshore Technology Development (OTD), we are committed to design and provide highly reliable, cost effective and robust monitoring systems for Offshore & Marine industries. We understand the importance of meeting tight budgets and deadlines to effective technical solutions. We work towards customer's wants and needs in providing cost effective solutions in both Offshore and Marine industries, optimising your vessel's safety & capabilities.

### VESSEL MOTION MONITORING

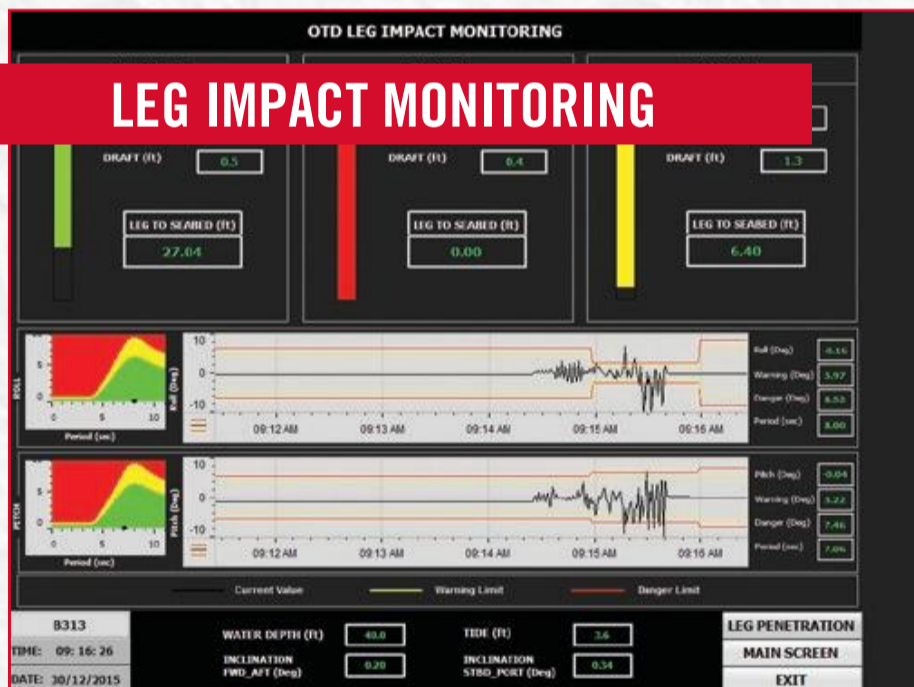


OTD vessel motion monitoring is designed to provide accurate monitoring of the vessel/platform motion during towing operation in the harsh sea environment with real time comparison of vessel motion against the critical design limits.

By ensuring safe operation of vessels in any harsh conditions at sea, this cost effective system keeps the vessel well within its limits of monitoring the whole operation.

The system consists of a central computer, which communicates with motion sensors through wireless communication. The portability of the system allows easy transfer and quick installation of the system on different vessels as and when required.

### LEG IMPACT MONITORING

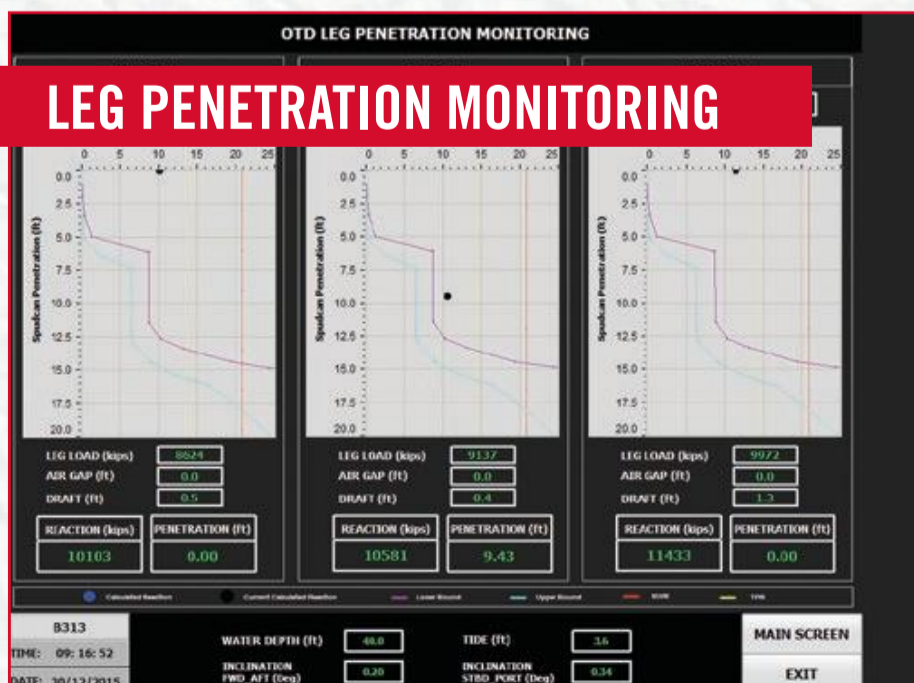


During installation of jack-up vessel, the leg impact monitoring system calculates the distance from leg bottom to seabed for each leg while tracking the motion of the vessel against the allowable limits for the given sea state and environment conditions.

The system utilises water depth, air gap sensor and leg length sensor to determine the distance between spudcan and seabed and alert the operator if the vessel motion is reaching the allowable limits.

The system consists of a central computer, which communicates with sensors through wireless communication. The portability of the system allows easy transfer and quick installation of the system on different vessels as and when required.

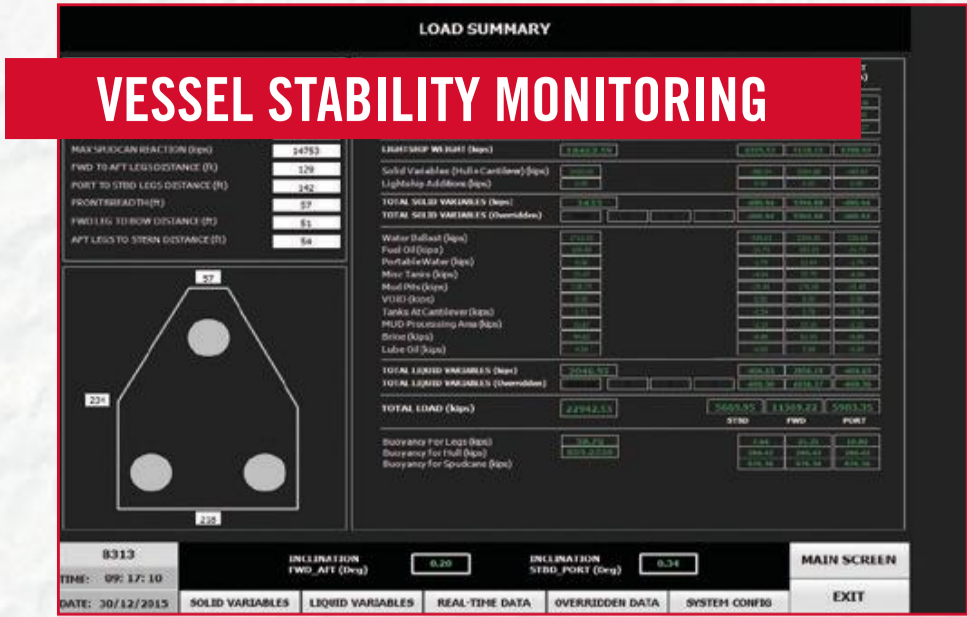
### LEG PENETRATION MONITORING



During preloading operation of the jack-up vessel, OTD leg penetration system monitors the leg reaction on each leg against the vessel's penetration curves.

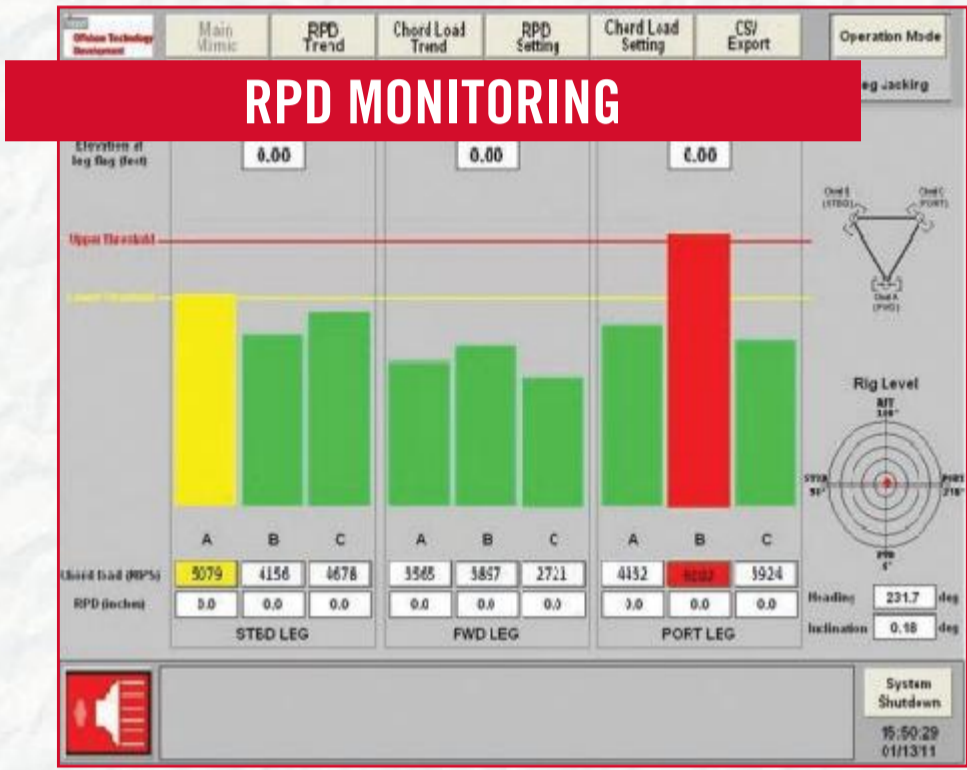
The system utilises water depth and air gap sensor to determine the penetration on each leg and alert the operator if the reaction on any leg is reaching the boundary limits, thereby making the preload operation safer and more reliable.

The system consists of a central computer, which communicates with different sensors through wireless communication. The portability of the system allows easy transfer and quick installation of the system on different vessels as and when required.



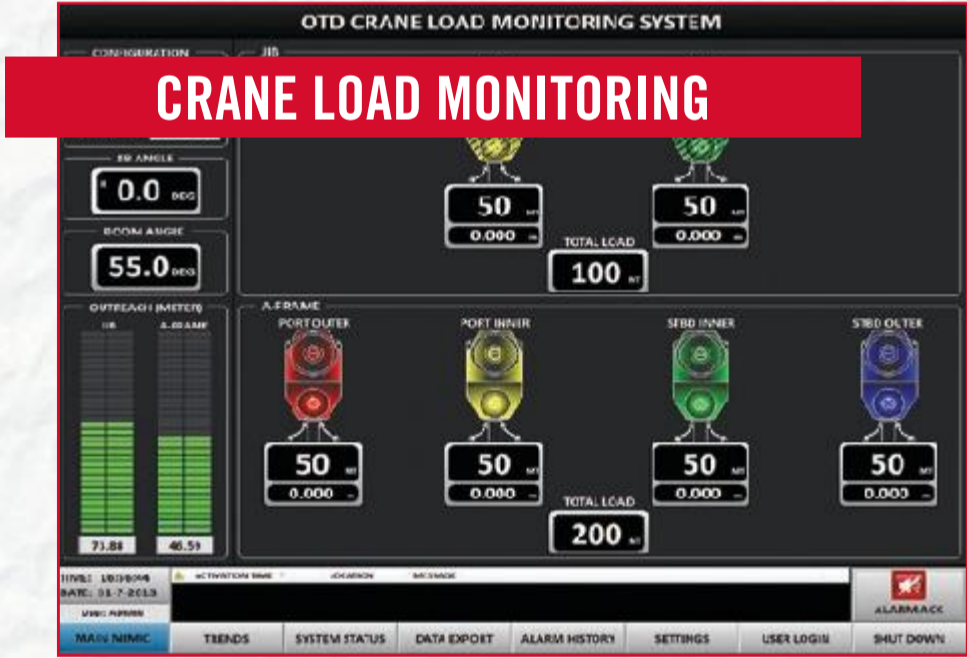
OTD vessel stability monitoring system is capable of performing calculations of loads exerted on the platform for any given operation and generating a comprehensive report for the barge engineer to plan out his activities during vessel installation.

The system also allows the rig crew to efficiently plan their daily operation and execute their activities safely.



Over the year, there have been several incidents when the bracings of truss-framed legs of jack-up rigs have been damaged due to effect of large Rack Phase Difference (RPD). The Rack Phase Difference (RPD) is defined as the relative vertical position of the corresponding rack teeth at each of the three chords of a particular leg. Some common causes of RPD encountered during jacking include re-installation on old footprints, punch-through and non-uniform seabed conditions.

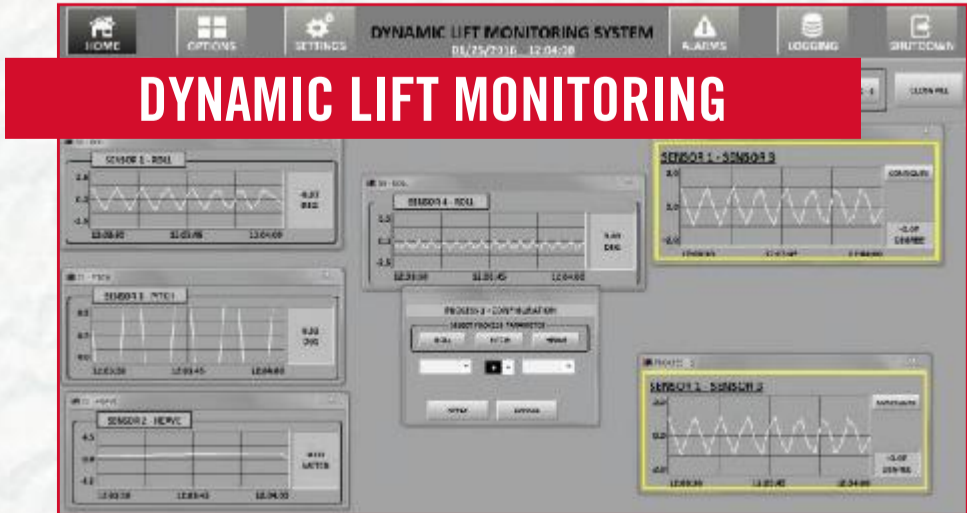
OTD RPD Monitoring system is designed to work with any type of jacking system as a stand alone system for new installation or retrofit projects. This system utilises a number of rotatory sensors to track the travelling distance on each chord and simultaneously compute the RPD for each leg. The operator is able to set the RPD allowable limits into the system so as to alert the operator when the RPD exceeds the limits.



OTD crane load monitoring system is a highly reliable custom-built system for monitoring the load on various cranes and holding platforms in the offshore and marine industry.

Being applicable with any type of crane, the crane load monitoring system is a complete solution which offers continuous tracking of the individual hoist load, computation of corresponding outreach and monitoring of total lifting load based on the design load limits.

The system can be interfaced with the hoist control system to provide the necessary cut off signal such that the safety of the vessel is not compromised, ensuring continuous, smooth and safe lifting operation.



OTD dynamic lift monitoring system is designed for transfer of cargo between ships. The system utilises the latest wireless technology to provide real-time motion information of the primary and target vessels and assist the crane operator in lifting and landing the cargo with reduced load impacts and rope tensions.

The system can also be applied to transfer of cargo between floating and fixed platforms.

# TRACK RECORDS

1998	Galaxy II	2009	Greatdrill Chitra	2013	Dynamic Vision
1999	Galaxy III	2010	PV Drilling II	2013	Transocean Ao Thai
2000	Ensco 101	2010	Rowan Viking	2013	Laurus
2002	Ensco 102	2010	Rowan Stavanger	2013	La Santa Maria
2002	Ensco 104	2010	PV Drilling III	2013	La Covadonga
2002	Ensco 105	2010	Rowan Norway	2013	Les Hat
2003	Beacon	2010	West Callisto	2013	AOD III
2004	Tonala	2010	PV Drilling II	2014	ArabDrill 60
2005	Al-Hail	2010	Rowan Viking	2014	UMW Naga 5
2005	Ensco 106	2010	Rowan Stavanger	2014	Dukhan
2006	Deep Driller 2	2010	PV Drilling III	2014	Ensco 122
2006	Ensco 107	2010	Rowan Norway	2014	Jindal Explorer
2006	ArabDrill 30	2010	West Callisto	2014	Asian Hercules III
2006	Deep Driller 3	2011	Peter Godovanets	2015	Yunuen
2006	COSLCraft	2012	Seafox 5	2015	Kukulkan
2007	Deep Driller 5	2012	SAR 202	2015	Ensco 110
2007	Sea Drill 4 (West Prospero)	2012	Nezalezhnist	2015	Cantarell I
2007	Paradise 400	2012	AOD I	2015	Cantarell II
2007	Ensco 108	2013	AOD II	2015	Cantarell III
2008	Ensco 109	2013	Discovery Triumph	2015	Cantarell IV
2008	Deep Driller 6	2013	Discovery Resilience	2015	PV Drilling VI
2008	COSL Boss	2013	UMW Naga 4	2015	UMW Naga 8
2008	Discovery I	2013	ArabDrill 50	2015	TS Topaz
2008	West Ariel	2013	Transocean Siam Driller	2015	Paraiso I
2008	Virtue I	2013	Transocean Andaman	2015	Paraiso II
2008	Ocean Scepter	2013	Primus	2015	ArabDrill 70
2009	Deep Driller 8	2013	Ensco 120	2016	Halul
2009	COSL Strike	2013	Ensco 121		
2009	Vasumati	2013	Hakuryu-11		



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